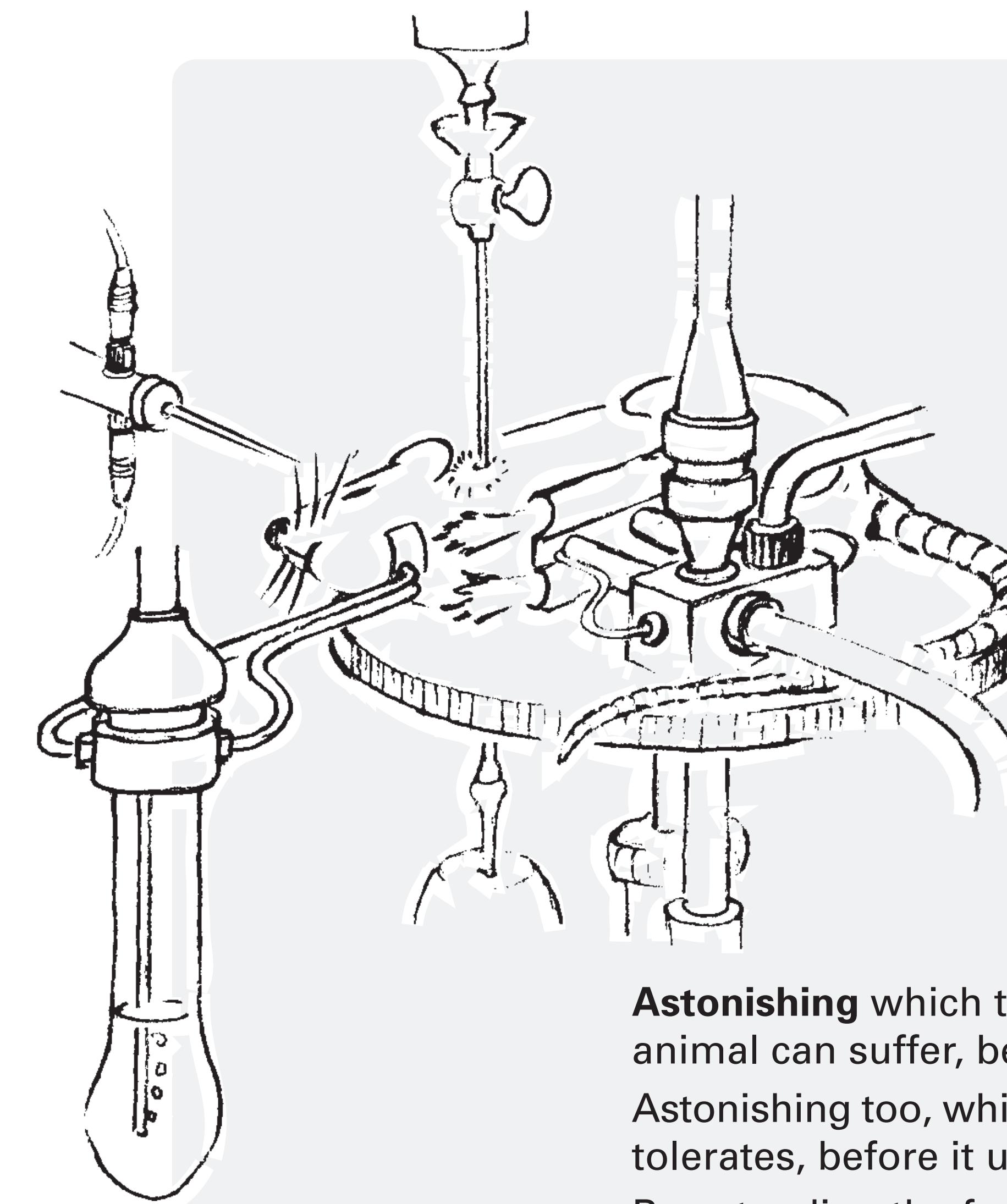
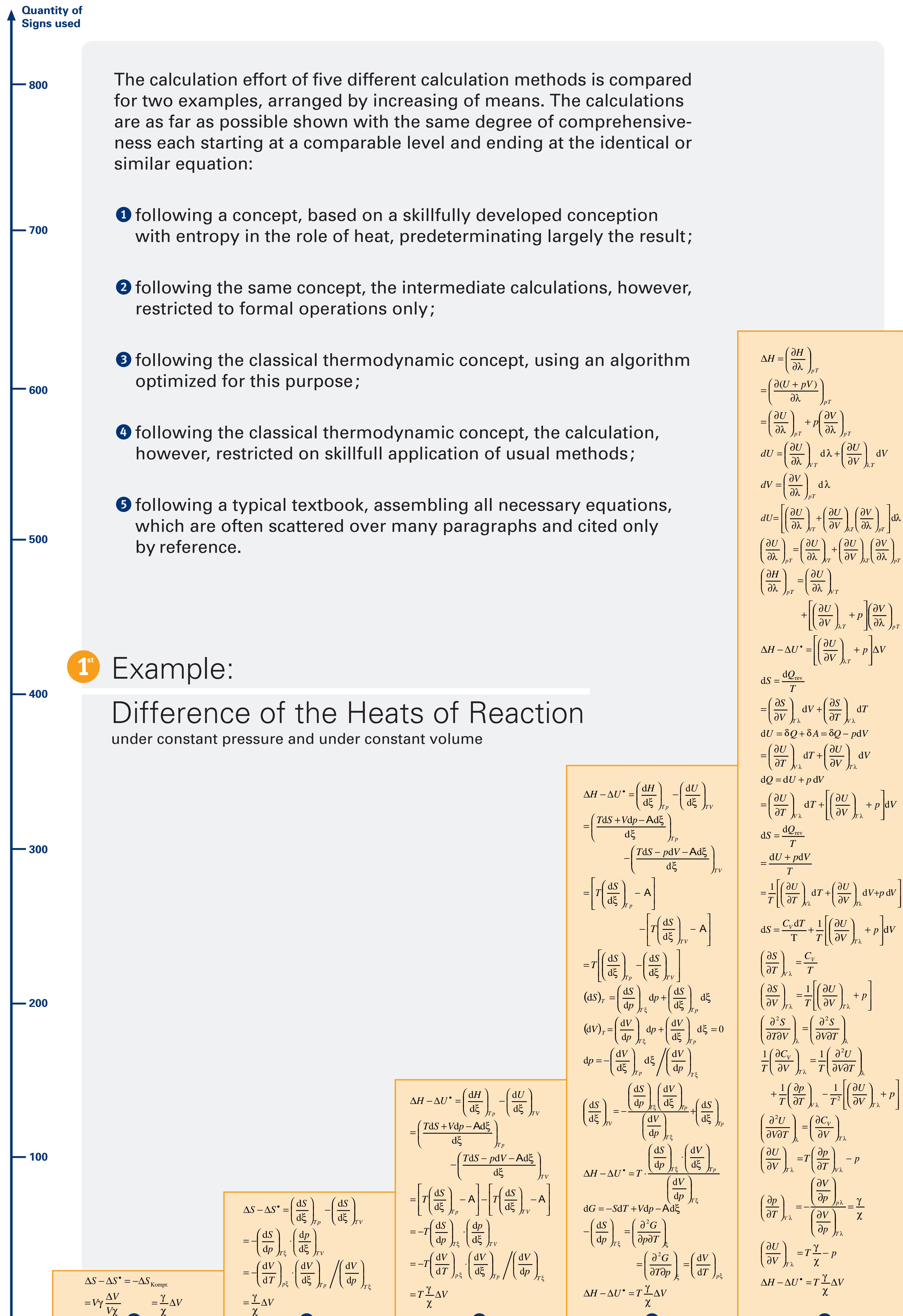


THE EFFICIENCY OF CLASSICAL THERMODYNAMICS



Astonishing which tortures an experimental animal can suffer, before it will die.

Astonishing too, which manipulations a theory tolerates, before it ultimately fails.

By extending the formalism even severe deficiencies can be successfully compensated.

2nd Example:

Temperature Coefficient of the Heat Evaporation

$\left(\frac{dp}{dT} \right)_{A\xi} = \left(\frac{dp}{dT} \right)_V = \left(\frac{dS}{dV} \right)_T$ $= \Delta S / \Delta V$ $\left(\frac{d\Delta S}{dT} \right)_{A\xi} = \Delta \check{C} - \Delta(V\gamma) \cdot \frac{\Delta S}{\Delta V}$	$\left(\frac{d\Delta S}{dT} \right)_{A\xi} = \left(\frac{d\Delta S}{dT} \right)_{p\xi} + \left(\frac{d\Delta S}{dp} \right)_{T\xi} \left(\frac{dp}{dT} \right)_{A\xi}$ $= \Delta \left(\frac{dS}{dT} \right)_{p\xi} + \Delta \left(\frac{dS}{dp} \right)_{T\xi} \left(\frac{dV}{dV} \right)_{pT}$ $= \Delta C_p + \Delta \left(\frac{Vdp + TdS - Ad\xi}{dp} \right)_{T\xi}$ $\cdot \left(\frac{dS}{d\xi} \right)_{pT} / \left(\frac{dV}{d\xi} \right)_{pT}$ $= \Delta C_p + \Delta \left[V + T \left(\frac{dS}{dp} \right)_{T\xi} \right] \frac{\Delta S}{\Delta V}$ $= \Delta C_p + \left[\Delta V - T \Delta \left(\frac{dV}{dT} \right)_{p\xi} \right] \frac{\Delta S}{\Delta V}$ $= \Delta C_p + \Delta S - T \Delta S \cdot \frac{\Delta(V\gamma)}{\Delta V}$	$\Delta H = \left(\frac{dH}{d\xi} \right)_{pT}$ $= \left(\frac{Vdp + TdS - Ad\xi}{d\xi} \right)_{pT}$ $= T \left(\frac{dS}{d\xi} \right)_{pT}$ $= T \Delta S$ $\left(\frac{d\Delta H}{dT} \right)_{A\xi} = \Delta C_p + \frac{\Delta H}{T} - \Delta H \frac{\Delta(V\gamma)}{\Delta V}$	$\left(\frac{d\Delta H}{dT} \right)_{koex} = \left(\frac{\partial \Delta H}{\partial p} \right)_T$ $\Delta G = 0$ $d(\Delta G) = 0$ $dH_i = TdS_i + V_i dp$ $dG_i = -S_i dT + V_i dp$ $G_i = H_i - TS_i$ $dS_i = \left(\frac{dS_i}{dT} \right)_p dT + \left(\frac{dS_i}{dp} \right)_T dp$ $\Delta G = \Delta H - T \Delta S = 0$ $\Delta S = \frac{\Delta H}{T}$ $d(\Delta G) = \Delta(dG)$ $= -\Delta S dT + \Delta V dp = 0$ $dp = \frac{\Delta H}{T \Delta V} dT$ $- \left(\frac{dS_i}{dp} \right)_T = \frac{\partial^2 G_i}{\partial p \partial T}$ $= \frac{\partial^2 G_i}{\partial T \partial p} = \left(\frac{dV_i}{dT} \right)_p = V_i \gamma_i$ $C_{pi} = \left(\frac{dH_i}{dT} \right)_p = \left(\frac{T dS_i + V_i dp}{dT} \right)_p$ $= T \left(\frac{dS_i}{dT} \right)_p$ $dS_i = \frac{C_{pi}}{T} dT - V_i \gamma_i dp$ $dH_i = C_{pi} dT + [V_i - TV_i \gamma_i] dp$ $\Delta(dH) = \Delta C_p dT + [\Delta V - T \Delta(V\gamma)] dp$ $d(\Delta H) = \left[\Delta C_p + [\Delta V - T \Delta(V\gamma)] \frac{\Delta H}{T \Delta V} \right] dT$ $\left(\frac{d\Delta H}{dT} \right)_{koex} = \Delta C_p + \frac{\Delta H}{T} - \Delta H \frac{\Delta(V\gamma)}{\Delta V}$	$\frac{\partial \Delta H}{\partial p \partial T} = \left(\frac{\partial \Delta H}{\partial p} \right)_T$ $\left(\frac{\partial H}{\partial p} \right)_T = V - T \left(\frac{\partial V}{\partial T} \right)_p$ $dL_p = (C_{p,D} - C_{p,fl}) dT$ $+ \left[V_D - T \left(\frac{\partial V_D}{\partial T} \right)_p - V_{fl} + T \left(\frac{\partial V_{fl}}{\partial T} \right)_p \right] dp$ $= \Delta C_p dT + \left[\Delta V - T \left(\frac{\partial \Delta V}{\partial T} \right)_p \right] dp$ $\left(\frac{\partial L_p}{\partial p} \right)_{koex} = \Delta C_p + \left[\Delta V - T \left(\frac{\partial \Delta V}{\partial T} \right)_p \right] \frac{dp_s}{dT}$ $\mu_D = \mu_{fl}$ $d\mu_D = d\mu_{fl}$ $d\mu = \left(\frac{\partial \mu}{\partial p} \right)_T dp + \left(\frac{\partial \mu}{\partial T} \right)_p dT$ $dG = -S dT + V dp + \mu dn$ $\frac{\partial^2 G}{\partial n \partial T} = \frac{\partial^2 G}{\partial T \partial n}$ $\frac{\partial^2 G}{\partial n \partial p} = \frac{\partial^2 G}{\partial p \partial n}$ $\left(\frac{\partial \mu_i}{\partial T} \right)_{p n_i} = -S_i$ $\left(\frac{\partial \mu_i}{\partial p} \right)_{T n_i} = V_i$ $d\mu_D = V_D d p_s - S_D dT$ $= d\mu_{fl} = V_{fl} d p_s - S_{fl} dT$ $\left(\frac{dp_s}{dT} \right)_{koex} = \frac{S_D - S_{fl}}{V_D - V_{fl}}$ $\left(\frac{dp_s}{dT} \right)_{koex} = \frac{L_p}{T \cdot (V_D - V_{fl})}$ $\left(\frac{dL_p}{dT} \right)_{koex} = \Delta C_p + \frac{L_p}{T} - L_p \underbrace{\left(\frac{\partial \ln \Delta V}{\partial T} \right)_p}_{\frac{\Delta(V\gamma)}{\Delta V}}$
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Degree of Restriction